VALIDATION REPORT



1.	Title of	Higher Certificate in Automation and Robotics
1.	Programme(s):	BEng in Automation and Robotics
	(incl. Award Type and	
	Specify Embedded	
	Exit Awards)	
2.	NFQ Level(s)/	Levels 6, 7
۷.	No. ECTS:	120/180 ECTS
3.	Duration:	2/3 years
3. 4.	ISCED Code:	0714
4. 5.		
5. 6.	School / Centre:	School of Engineering
	Department:	Department of Mechanical and Industrial Engineering Differential Validation
7.	Type of Review:	
8.	Date of Review:	10 th May 2022
9.	Delivery Mode:	Blended
10.	Panel Members:	Dr Brendan O'Donnell, Niall Morris, Camila D Bastiani, Neasa
	Description of the	Flannery, Dr Des Foley
11.	Proposing Staff:	Carine Gachon
		Aurora Dimache
		David Gorman
		Jack Saad
		Stephen Foy
		Gabriel Farragher
		Michael Kelly
		Niall O'Connor
12	Dette de fei	Nireeksha Karode (not sure if she attended)
12.	Rationale for	Following a request from industry, the programmes were developed
	Changes:	and approved in 2020 as a part-time programme where students
		complete 60 credits per year. All students in the programme are
		employed in the manufacturing industry and are released by their
		employer to attend classes. They undertake 20 credits in each of the
		two traditional academic semesters and a 20 credits Industry module
		in a third semester. The experience of delivering the programme since
		inception has suggested the necessity for some changes. In addition,
		following feedback from students and the newly appointed internal
		examiners, a number of issues have been identified such as:
		• lack of relevance of some topics, duplication, gaps in
		material,
		 learning outcomes too ambitious,
		 sequencing of modules and industry training
42		
13.	Overview of Changes:	It is proposed to move the module Programming with Python to year
		2 and move Programming with C& C++ to year 3. The C& C++ module
		is more suited to the level 7 as some concepts like object-oriented
		design, basic algorithm are better introduced if students have already
		done some programming. Also, moving Python programming in years
		allows contextualisation of programming as students will program
		robotic arms.

		-	otors are introduced is being moved to on about motors first and then they will emester 2.	
		the programme was divided in strands each strand. Then, each strand was rlap and gaps. Special attention has e Industry modules. The experience of the need for more structure in the ct as well as more integration with the x Sigma module in year 2 and 3 included in the Industry module were ecturers, who attended the training, in The flow between trainings, projects, alysed and the training needs adapted.		
		Changes outlined in full in Appe	endix A.	
14.	Resource	No additional resources are rec	quired.	
	Implications:			
15.	Findings and	General:		
	Recommendations:			
			ed changes with the commendations	
		listed below and subject to the following condition(s) and		
		recommendation(s):		
		Commendations:		
			proactive and timely approach to this	
		review	prodetive and timely approach to this	
		Special conditions attaching to	approval (if any):	
		No conditions		
		Recommendations of the pane	l in relation to award sought:	
			mme board will need to review level	
		of content and expectation bei		
		SDG Goals need to brought out	more in the document	
	540 A 1			
16.	FAO: Academic	Approved:		
	Council:	Approved subject to	X	
		recommended changes:	+	
	Signed:	Not approved at this time:		
	Signed.	Buch Down	Dermond Hay	
		Chair	Secretary	

				Αμ	opendix A				
Appendix AStrand	Mathematics	Instrumentati on	Mechanical Design of an automated cell	PLC	Robotics	Analog Control (Temperature and Motion)	Programming	System Integration	Transversal skills
Stage									
1	Mathematics Fundamentals	Electrical Principles and Automation Industry Module 1	CAD Engineering Science Electrical Principles and Automation	Electrical Principles and Automation Industry module 1	Industry module 1				LIS Industry Module 1
2	Mathematics 2	Instrumentati on & Control Industry module 2	Automation 2	Automation 2 Industry Module 2	Programming with Python	Instrumentati on & Control	Programming with Python (Previously in year3)	Networking Technology	Regulatory Affairs Project Management Industry Module 2
3	Six Sigma Green Belt Quality	Industry module 3	Mechanical systems Industry module 3	Industry Module 3	Industrial Robotics (previously) Automation 3) Industry module 3	Control Systems Industry module 3	Programming with C & C++ (Previously in year 2)	Internet of Things Project	Six Sigma Green Belt Quality Industry Module 3

Mathematics strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	Mathematics Fundamentals	 Perform simple arithmetic operations. Work with mathematical formula and functions. Draw graphs of standard functions and interpret graphs. Work with trigonometric, logarithmic, and exponential functions in solving problems. Perform simple differentiation. Perform calculations involving complex numbers in Cartesian and polar form. Work with vectors and matrices. Work with data and perform simple statistical analyses. 	No change
2	Mathematics 2	 Differentiate single variable functions requiring a combination of rules. Determine the partial derivatives of functions of two variables. Apply differentiation to solve rates of change and lecognize lon problems. Select and apply appropriate techniques of integration to evaluate integrals. Solve first order differential equations by direct integration and separation of variables. Analyse the behaviour of systems and processes in engineering to lecognize when differential equations are appropriate, formulate the problem, creatively model these behaviours in order to solve the problems, interpret and clearly communicate the results. 	No change

		7. Apply the rules of probability and use probability models for data analysis.	
3	Six sigma Grenn Belt Quality	1. Explain the Define, Measure, Analyse, Improve and Control steps in Six Sigma. Describe lean engineering and the origins of Six sigma.	The module learning outcomes were changed to align with Professional Accreditation requirements, and the syllabus of the module has
	Name changed to Six Sigma Quality as the	2. Use 'Define' phase tools to decide on the process improvement of a Six Sigma project	been stream-lined to adapt to the requirements of the programme.
	Green Belt certification is not included.	3. Determine the current performance using a variety of 'Measure' tools	The TLA and Assessment strategy were reviewed to reflect the way the module is delivered.
		4. Use the 'Analyse' tools, including inferential statistics to determine the issues to be addressed.5. Use the 'Improve' tools, to experiment and assess	
		 the process optimisation. 6. 'Control' the process to verify the variances are corrected, select appropriate statistical process control (SPC) techniques. 	

Instrumentation strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	Electrical Principles	1. Analyse basic circuits using the fundamental laws	3. Illustrate and discuss the technology and use of
	and Automation	of electrical science.	common actuators.
		2. Describe the technology and use of common	6. Specify, select, build, program and troubleshoot
		electrical and electronic components.	basic PLC circuits.
		3. Illustrate and discuss the technology and use of	
		common sensors and actuators.	Rationale:
		5. Apply basic safety principles	The PB decided to introduce PLC from first year
		6. Specify, select, build and troubleshoot basic	as it is the principal controller used in industry.
		electrical/instrumentation circuits using	Students will learn the electrical and electronic
		microcontrollers.	background required to understand the sensor
			technology. They will use sensors in their PLC
		LO4 relates to the Mechanical Design Strand	circuits, but the detailed study of sensors and
			sensor technology will be covered in year 2.
			The syllabus was updated to reflect the LO
			changes.
1	Industry module 1	5. Undertake a basic technical project demonstrating	There is no change to the LO, but the brief of the
		a skill acquired in their training.	project was expanded on to make sure that students
			use inputs (sensors). In first year, the equipment
		Other LOs relate to the Transversal skills and	will be supplied by GMIT to add consistency into
		robotics strands.	the projects.
			New text added
			The scope of this project will be limited to a single
			operation. The output will be the production of an
			artefact that the student will demonstrate to their
			industry mentor and academic supervisor. The
			project should include a PLC and a minimum of 4
			inputs and outputs. Students should have a 2D

			CAD wiring diagram, a 3D model of their design. A minimum of one fixture should be 3D printed.
2	Instrumentation and Control	 Explain the mode of operation of key sensors and transducers and implement appropriate calibration and signal conditioning. Measure, record and analyse data with a range of sensors and transducers. Interpret instrument specifications correctly, verify that instruments are operated safely and within specifications. Choose the optimum sensor and /or instruments for specific applications and make sensible decisions on the purchase of suitable scientific equipment to meet requirements. 	No change to the Instrumentation LO, the 3 of the 4 other LOs in the original module were removed as they were far too ambitious for a 5 credits module and were more specific to Control Systems. This module will introduce the overall concept of control systems but will concentrate on the instrumentation side. (See control system strand for more details)
		Four other LOs relate to Control Systems	
2	Industry module 2	4. Program and troubleshoot a PLC, integrating inputs and outputs.	4. Program and troubleshoot a PLC, integrating inputs and outputs. Second LO added :
		Other LOs relate to the Transversal skills strand.	5. Design and build an automated rig for a basic operation, including safety features
			The brief of the project was expanded on to give a better structure to the delivery of the project and increase consistency between projects. New text:
			Students will have to draw up the project specification by the end of week 4 of semester 2, to be agreed with their academic supervisor and their industry mentor by week 6, The bill of material

			should then be submitted by week 8 of semester 2. The student is expected to be ready to start the project as early as possible into the Industry Block. The scope of this project will be to demonstrate their knowledge of designing, building and programming an automated system that includes a minimum of 8 inputs and 8 outputs. An HMI and element of networking must also be included. Safety features must be present in the project. The output will be the production of an artefact that the student will demonstrate to their industry mentor and academic supervisor. Students should have a 2D CAD wiring diagram of an input card and a 3D CAD model of a minimum of one component of their project
3	Industry module 3	 Design an automated cell integrating a robotic arm, PLC control, vision systems and safety features This LO is covering Instrumentation, PLC, Robotics, Mechanical Systems and Control Systems strands. Other LOs relate to the Transferrable skills strand. 	 Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features. Drive was added to reflect the content of the Control System module. The Description of the project was expanded on to give more structure to the delivery and increase consistency. New text: Students will have to draw up the project specification by the end of week 4 of semester 2, to be agreed with their academic supervisor and their industry mentor by week 6, The bill of material should then be submitted by week 8 of semester 2. The student is expected to be ready to start the project as early as possible into the Industry Block.

The output of the project will be the design of an automated cell that will comply with industry standards and safety regulations. The cell should integrate a minimum of three hardware element (PLC, Robotic arm, drive, I/O link and/or vision system), demonstrate the manipulation of data of a minimum of two process variables as well as visualisation on HMI. In the programming of the PLC, students should demonstrate ability to use more than one programming language (Ladder, SFC, structure text, etc).
The technical project is also integrated with the Six Sigma module and the DMAIC project. In the assessment strategy more weight is given to the technical project, as some of the DMAIC project is assessed in the Six Sigma module.

Mechanical Design of an Automated Cell strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	CAD	 Use three dimensional solid modeling software (CREO 3.0) in the design of engineering components. Apply engineering graphics standards. Use various technical commands and be able to select the appropriate methodology (design intent) required for the creation of a solid model. Create drawing files displaying orthographic layouts from the solid model as well as dimensioning and applying dimensional and geographic tolerances to the drawing file. Select and use the optimum software techniques to create parts and assemblies models. Use standards parts libraries for the selection of appropriate standard components in the design / assembly process. Teaching and Learning Strategies 	No change
	Engineering Science	 Identify the physical principles relevant to specified problems. Solve theoretical and practical problems. Work on optical, mechanical, and thermodynamic experiments using best laboratory practices. Select appropriate instrument(s) for specific tests/measurements. Identify anomalous results and make decisions regarding the source of the anomaly. 	No change to the learning outcomes Assessment breakdown

	Electrical Principles and Automation	 6. Record results in compliance with standard practice including measurement uncertainties. 7. Conduct experiments in accordance with safe practice. 8. Independently read instructions and accurately follow a pre-determined methodology. All Los in this strand 4. Explain the basic principles of electrical power generation. 	No change
		All other Los in the Instrumentation and PLC strands	
2	Automations 2	 Demonstrate competence in standards used in schematic symbols and drawing layouts Construct schematic diagrams for basic industrial automated applications using the correct standards in pneumatic, hydraulic, electrical, electro-pneumatics, electro-hydraulics areas Simulate circuits to verify operation. Analyse circuit design for faults and errors Optimise circuit design Other LO's in the PLC strand. 	 Demonstrate competence in standards used in automation, including machine building standards Construct schematic diagrams for basic industrial automated applications using the correct standards in pneumatic, electrical, electro- pneumatics areas Analyse and 8ptimize circuit design using simulation. The reference to Machine Building Standard was added in LO 1following feedback from Industry. LO 3, 4 and 5 were consolidated into 1.
3	Mechanical Systems	 Describe the industrial uses, feasibility and cost effectiveness of types of mechanical systems Examine motors to show the construction, operation and applications of each Illustrate and discuss mechanical systems components technology and anatomy 	 Los to 2 to 4 were reworded to better reflect the Industry need. 5 and 6 were removed as these LO are already covered in other modules. 2. Select the components of a mechanical system for different automated applications 3. Define actuators' specifications for different applications.

	 4. Inspect drive systems to show the construction, operation and applications of each 5. Analyse sensors to show the applications of each 6. Integrate sensors/actuators 	4. Define conveyors' specifications for different applications.
Industry module 3	1.Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features.	1. Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features.
	This LO is covering Instrumentation, PLC, Robotics, Mechanical Systems and Control Systems strands. Other LO's in the Transversal skills strand.	As the DMAIC project is being integrated with the Six Sigma module and the technical project, the breakdown of marks was changed to increase the weighting of the technical project

PLC strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	Electrical Principles and Automation	6. Specify, select, build and troubleshoot basic electrical/instrumentation circuits using microcontrollers.	6. Specify, select, build, program and troubleshoot basic PLC circuits.
			See Instrumentation strand for rationale
	Industry module 1	 3. Wire and troubleshoot a Programmable Logic Controller using best practice. 5. Undertake a basic technical project demonstrating a skill acquired in their training. LO 5 already featured in Instrumentation Other LOs relate to the Transversal skills and Robotics strands. 	There is no change to the LOs apart for the word "training" being replaced by the word "Programme" The brief of the project was expanded as described in the Instrumentation strand. The PLC training included originally included was moved to year 2 to better integrate with the advanced PLC module (Automation 2). The intro to PLC is now covered in Electrical principles and automation.
2	Automation 2	 6. Describe the industrial uses, feasibility and advantages/disadvantages of a PLC. 7. Describe PLC technology using the correct terminology 8. Construct ladder logic programmes using Boolean Logic, IOs, timers, counters, sequencing 	 4. Describe the industrial uses, feasibility and advantages/disadvantages of a PLC 5. Describe PLC technology using the correct terminology 6. Construct ladder logic programmes using Boolean Logic, IOs, timers, counters, sequencing, and advanced functions. Advanced functions were added to the last LO. As better integration of the OEM trainings and academic modules is allowing for more advanced
	Industry module 2	4. Program and troubleshoot a PLC, integrating inputs and outputs.	features to be included.4. Program and troubleshoot a PLC, integrating inputs and outputs.

		This LO already featured in Instrumentation Other LOs relate to the Transversal skills strand	Second LO added : 5. Design and build an automated rig for a basic operation, including safety features The brief of the project was expanded on to give a better structure to the delivery of the project and increase consistency between projects. See instrumentation strand for more details.
3	Industry module 3	 Design an automated cell integrating a robotic arm, PLC control, vision systems and safety features This LO is covering Instrumentation, PLC, Robotics, Mechanical Systems and Control Systems strands. Other LOs relate to the Transferrable skills strand. 	 Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features. Drive was added to reflect the content of the Control System module. The Description of the project was expanded on to give more structure to the delivery and increase consistency. See details in Instrumentation strand.

Robotics strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	Industry module 1	2. Operate a robotic arm in a safe manner.Other LOs relate to the PLC, Instrumentation and Transversal skills strands	 2. Program and operate a robotic arm in a safe manner. The Robotics training was originally divided between the three years and some of it was duplication from Automation 3. Students will complete all of the trainings on one type of robotic arm in year 1 and they will do a more advanced dedicated module in year 3 that will be based on a different brand of robotic arm and will also include the 3 D model and simulation.
2	Programming with Python (this module was originally in year 3 and now moved to year 2)	1. Develop Python code, incorporating fundamental programming principles and techniques.	 Develop Python code, incorporating fundamental programming principles and techniques, for robotic technology. Taking into consideration the feedback from students, the team decided to give more context to the programming module by using python to program robotic arms
3	Automation 3 This module is being renamed Industrial Robotics to highlight the focus of the module and to offer it as a stand-alone module.	 3. 3D modelling of cell design. Complete automation of cell and equipment used including valves, sensors, actuators, motors, robots etc. 4. Report the industrial uses, feasibility and cost effectiveness of robotic systems. 5. Illustrate and discuss robotics technology and anatomy 	 4. Program and troubleshoot a PLC, integrating inputs and outputs. Second LO added : 5. Design and build an automated rig for a basic operation, including safety features

		 6. Develop and simulate advanced robotic program using inputs and outputs 7. Describe the industrial uses of vision systems. 8. Integrate robotics/ vision systems with additional sensors/actuators 	The brief of the project was expanded on to give a better structure to the delivery of the project and increase consistency between projects. See instrumentation strand for more details.
3	Industry module 3	 Design an automated cell integrating a robotic arm, PLC control, vision systems and safety features This LO is covering Instrumentation, PLC, Robotics, 	1. Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features.
		Mechanical Systems and Control Systems strands. Other LOs relate to the Transferrable skills strand.	Drive was added to reflect the content of the Control System module. The Description of the project was expanded on to
			give more structure to the delivery and increase consistency. See details in Instrumentation strand.

Analog Control strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
2	Instrumentation and Control	 5. Explain the differences in performance between open- and closed-loop control systems and explain the principles involved in such systems. 6. Describe the function of a process controller and the use of proportional, derivative and integral control laws. Explain PID control and how such a controller can be tuned. 7. Define the term transfer function and explain how it is used to relate outputs to inputs for systems. 8. Model dynamic systems by means of differential equations. Characterise the response of first-order systems to inputs. 	 1. Explain the differences in performance between open- and closed-loop control systems and explain the principles involved in such systems. Tthe 3 other LOs in the original module were removed as they were far too ambitious for a 5 credits module and were more specific to Control Systems. This module will introduce the overall concept of control systems but will concentrate on the instrumentation side.
3	Control Systems	 Explain the differences in performance between different types of control systems and explain the principles involved in such systems. Give reasons for the implementation of P, PI or PID control. Assess the effect of dead time on the behaviour of a control system. Examine the uses of cascade control and feedforward control. Model 2nd-order physical systems using differential equations Represent 2nd-order system responses using Laplace Transform method. Design closed-loop feedback systems. 	 Explain the principles involved in different control systems and their differences in performance and applications Select the appropriate control strategy for a given application in process and motion control Specify the components for open loop and closed loop control for industrial use cases Develop process and motion control systems for industrial use cases learning outcomes for a 5 credit module was far too ambitious. Also the focus of the programme is

		 6. Analyse closed-loop control systems in terms of stability performance. 7. Specify system performance in terms of time-domain and frequency-domain response. 8. Analyse control systems in terms of steady-state error. 9. Design, set up, operate and analyse complex control systems. Set up and operate robotic systems. Model control system behaviour using suitable metho 	on Automation and the use of control systems in a manufacturing industry setting. Control systems concepts will be introduced in the context of their use in automation, specifically for temperature and motion control.
3	Industry module 3	 Design an automated cell integrating a robotic arm, PLC control, vision systems and safety features This LO is covering Instrumentation, PLC, Robotics, Mechanical Systems and Control Systems strands. Other LOs relate to the Transferrable skills strand. 	 Design an automated cell integrating hardware such as robotic arm, PLC controller, drive or vision systems as well as safety features. Drive was added to reflect the content of the Control System module. The Description of the project was expanded on to give more structure to the delivery and increase consistency. See details in Instrumentation strand.

Programming strand

Programming is covered in the PLC and Robotics strands as students learn to programme hardware. This strand relates to more generic programming languages.

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
2	Programming with	1. Develop Python code, incorporating fundamental	1. Develop Python code, incorporating
	Python	programming principles and techniques.	fundamental programming principles and
		2. Select, use and test a range of standard Python	techniques, for robotic technology.
	(this module was	language features and common libraries, using	2. Select, use and test a range of standard Python
	originally in year 3 and	professional development tools.	language features and common libraries, using
	now moved to year 2.	3. Apply software engineering principles in Python.	professional development tools.
	Python is a higher level	4. Design and debug code to address unforeseen	3. Apply software engineering principles in
	language so easier to	tasks.	Python.
	introduce first. Also,	5. Select and use Python modules in data analysis	4. Design and debug code to address unforeseen
	this allows for the	applications.	tasks.
	programming of robotic	6. Display an appreciation of good programming	5. Display an appreciation of good programming
	arms.	practice, style and ethics.	practice, style and ethics.
			LO 5 was removed as too ambitious for a level 6.
			The topic is covered in year 3 in the IoT Project
			module
			The assessment strategy was removed to better
2	Due e ne ne ne in e ereidte	1 Develop and delay have a more than a more than	scaffold students' learning.
3	Programming with	1. Develop and debug basic programs incorporating	No change to the LO as they were too ambitious
	C&C++	fundamental programming principles and techniques.	for a level6.
	(originally in year 2,	2. Select, use and test modern C & C++ core	The approximate starts are used in a difficulty hotter
	moved to year 3)	language and standard library features, using	The assessment strategy was modified to better
	Some of the LOs are	professional software and hardware development	scaffold students' learning.
	better suited to a Level	tools.	

7, in particular if	3. Apply basic algorithm design and documentation	
students have already	techniques.	l
experience of	4. Design & debug code to address unforeseen tasks.	l
programming.	5. Display an appreciation of good programming	l
	practice, style and ethics.	l
	6. Describe applications and principles of C & C++.	

Data integration strand

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
2	Networking Technology	 Discuss current network technologies, applications and emerging trends for industrial and business applications. Describe the Internet protocol suite (TCP/IP). Recognise and analyse Ethernet, Industrial Ethernet and wireless network architectures, devices and data. Select, configure and problem-solve networking elements in a practical application. Design, build and test a basic network in a practical application. Appreciate network management principles and challenges. 	No change
3	Internet of Things project	 Research an IoT based application area and create a project proposal, following general requirements. Discuss a selected IoT application area, including industry, trends, technologies, ethics. Investigate & select suitable hardware and/or software elements to use in a project, following general guidelines. Develop, integrate, build and test hardware and/or software elements of a project, on a specified Internet of Things development platform. Apply problem solving techniques to technical and other issues that arise in the context of a project. Manage project deliverables throughout the project timeline in an agile environment. 	LO8 was changed to include data capture, data storage and a data analytics which was removed from the Python programming module. 8. Demonstrate project technical functionality, including data capture, data storage and data analytics. Two assessments have been combined to reduce the workload.

7. Contribute towards a collaborative working	
environment, as well as work independently towards	
project goals.	
8. Demonstrate project technical functionality, and	
understanding of technical and mathematical	
concepts and implementations incorporated.	
9. Communicate project ideas, design and	
deliverables, using professional tools and guidelines.	

Transversal skills

Stage	Module name	Current Learning Outcomes mapping to this strand	Proposed Changes
1	Learning Innovation Skills	 Apply the basic principles of critical thinking/problem solving to engineering systems Demonstrate an enhanced capacity to communicate verbally in contexts relevant to an engineering environment Explain the ethical standards required of the professional engineer Demonstrate an ability to communicate via electronic media to the standards of the engineering industry Appraise, select, and apply appropriate learning strategies 	No change
	Industry module 1	 Comply with company's procedures and policies, and describe the company's ethical guidelines relating to the workplace, customers and the environment. Describe and explain manufacturing processes available in the work place. Integrate in the company work place, communicating and contributing as an individual and team member, and describe the company's organisational structure. Reflect on their experiential learning. LOs 2,3 and 5 relates to the PLC and Robotics strands 	No change to these LOS
2	Project Management	1. Apply the principles and methodologies of project management to their specialist discipline.	No change to this module.

	2. Apply project management techniques and systems	
	in their specialist discipline.	
	3. Recognise the complexities of team based	
	management.	
	4. Structure project or job tasks, schedule and	
	manage.	
	5. Apply engineering and project management	
	techniques to real problems in industry or laboratory	
	settings	
	6. Combine various aspects of the course in a	
	practical context through preparing and delivering	
	presentations / reports on the specification / scope,	
	planning and implementing of a project	
Industry module 2	1. Select the appropriate tools, methodologies and	No change to these LO. Two other Los relate to the
	techniques to solve manufacturing problems, and	technical project, specifically the Instrumentation
	design and implement solutions.	and PLC.
	3. Communicate findings to teams and management,	
	and work effectively as a team member.	
	4. Describe and communicate how the regulatory	
	constraints affect the operations of the company, and	
	how ethical considerations affect their conduct as a	
	technician.	
	6. Reflect on their experiential learning, and their	
	ability to solve problems using a structured technical	
	approach, and identify gaps.	
Six sigma Grenn Belt	1. Explain the Define, Measure, Analyse, Improve	The module learning outcomes were changed to
Quality	and Control steps in Six Sigma. Describe lean	align with Professional Accreditation
	engineering and the origins of Six sigma.	requirements, and the syllabus of the module has
Name changed to Six	2. Use 'Define' phase tools to decide on the process	been stream-lined to adapt to the requirements of
Sigma Quality as the	improvement of a Six Sigma project	the programme.
Green Belt certification	3. Determine the current performance using a variety	The TLA and Assessment strategy were reviewed
is not included.	of 'Measure' tools	to reflect the way the module is delivered.

4. Use the 'Analyse' tools, including inferential	
statistics to determine the issues to be addressed.	
5. Use the 'Improve' tools, to experiment and assess	
the process optimisation.	
6. 'Control' the process to verify the variances are	
corrected, select appropriate statistical process	
control (SPC) techniques.	